

Tutorials: Groups of 2/3

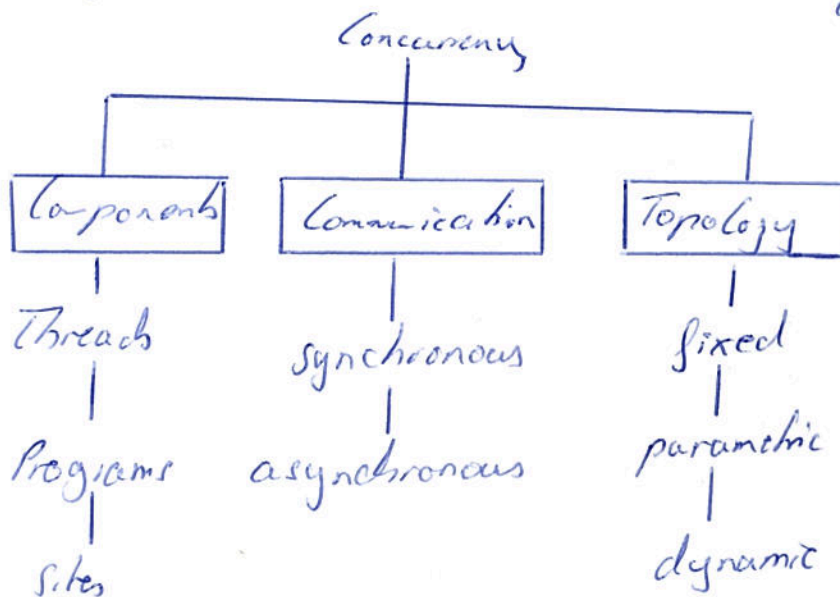
- Exercises: Out Tuesday, In Monday, Wednesday tutorial.
- Exercises marked + for correct answer (need not be perfect)
- 60% of exercises need + to be admitted to the exam
- Exercises start this week
 - ↳ Georgel gives more introduction to Petri nets.
- 2 presentations on the board required

Exam:

- Oral / written will be decided next week.

Concurrent systems:

Spectrum



This lecture:

Part I

Multi-threaded programs

Part II

Static networks

Part III

Dynamic networks

Multi-threaded programs

↳ Threads, synchronous / asynchronous communication, fixed / parametric topology

↳ Dekker's / Peterson's mutex algorithms

↳ Dijkstra's semaphore

Static networks:

↳ Networking sites, asynchronous message passing, fixed topology (parametric message channels)

↳ Alternating bit protocol

Dynamic networks (Remote objects):

- ↳ OO-programs, synchronous communication, dynamic topologies
- ↳ Logia protocol for client-server architectures

Goal of this course:

- Learn about automata models for these concurrent systems

FBDP:

- ↳ NFA/DFN for finite state programs
- ↳ Pushdown automata for recursive programs

Here:

- ↳ Automata for concurrent systems.

- Learn how to analyse them automatically:

Approach to verification:

- ↳ Start from Java RMI program, class in concurrency library, ...
- ↳ Compile down to automata
- ↳ Apply procedures you learned to infer correctness.

Overview of the course content:

Part I: Multi-threaded programs

Goal: Verify multithreaded programs

Examples: • Mutual exclusion protocols
• Programs with shared memory, caches

Automata model: (Unbounded) Petri nets

- ↳ finitely many types of threads/components
- ↳ potentially unboundedly many instances (parametric)
- ↳ programs do not use heap structures (lists, trees, ...), no recursion

Verification problems:

↳ Safety properties: Is an undesirable state reachable?

- Mutex fails if two threads in critical sections
- Bounded Petri nets (finite state): Fast algorithms
- Unbounded Petri nets (infinite state): Decidability.

↳ Invariants: Does some relation among variables always hold?

Example: Dijkstra's semaphore

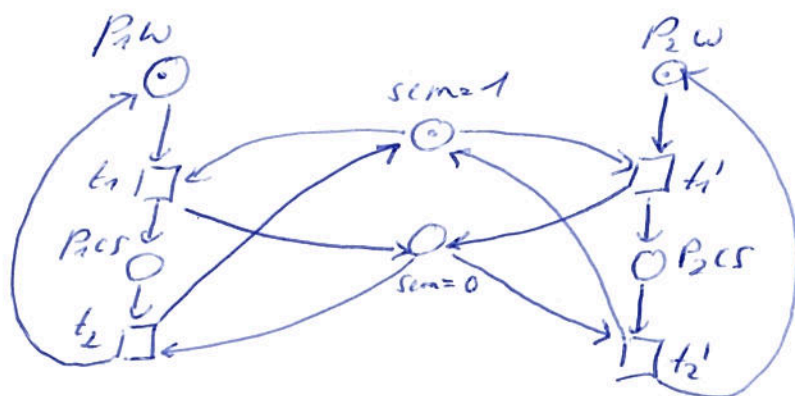
Semaphore: Boolean variable, initially 1

2 threads: ↳ Try to enter their critical sections

↳ Proc sets semaphore from 1 to 0

↳ Free sets semaphore from 0 to 1

Automaton model:



Places \circ \approx control locations of finite automata

Transitions \square + arcs \approx transitions of finite automata
+ their synchronisation

(Remember parallel product $\mathcal{A}_1 \parallel \mathcal{A}_2$)

Marking \approx state of an automaton

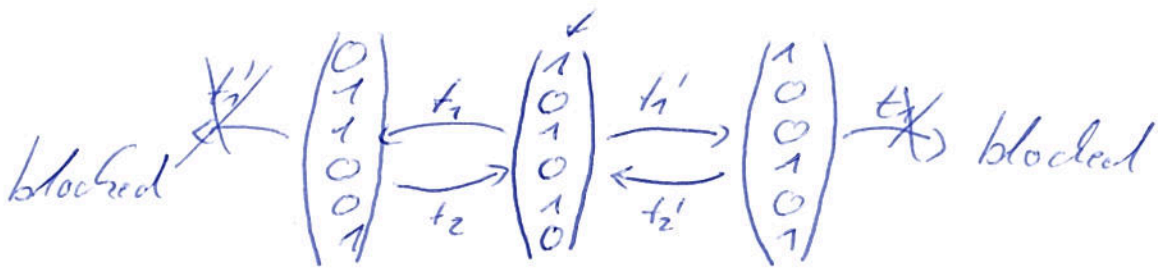
↳ Tokens • are not ordered.

17 little bit of semantics:

↳ Markings are vectors

$$\begin{pmatrix} 1 \\ 0 \\ 1 \\ 0 \\ 1 \\ 0 \end{pmatrix} \begin{matrix} p_1W \\ p_1S \\ p_2W \\ p_2S \\ sem=1 \\ sem=0 \end{matrix} \quad \text{over } \mathbb{N}^{|Places|}$$

- ↳ Transitions
 - remove a token for every incoming arc
 - produce a token for every outgoing arc
 - block if there are not enough tokens available



Reachability problem:

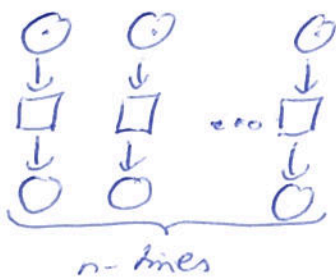
Given: PN N and a (bad) marking M .

Question: Is M reachable from initial marking M_0 of N ?

Study algorithmic techniques to answer this question.

Unfoldings:

Problem: State space grows exponentially in degree of concurrency



yields 2^n reachable markings.

Not a good idea to compute them explicitly.

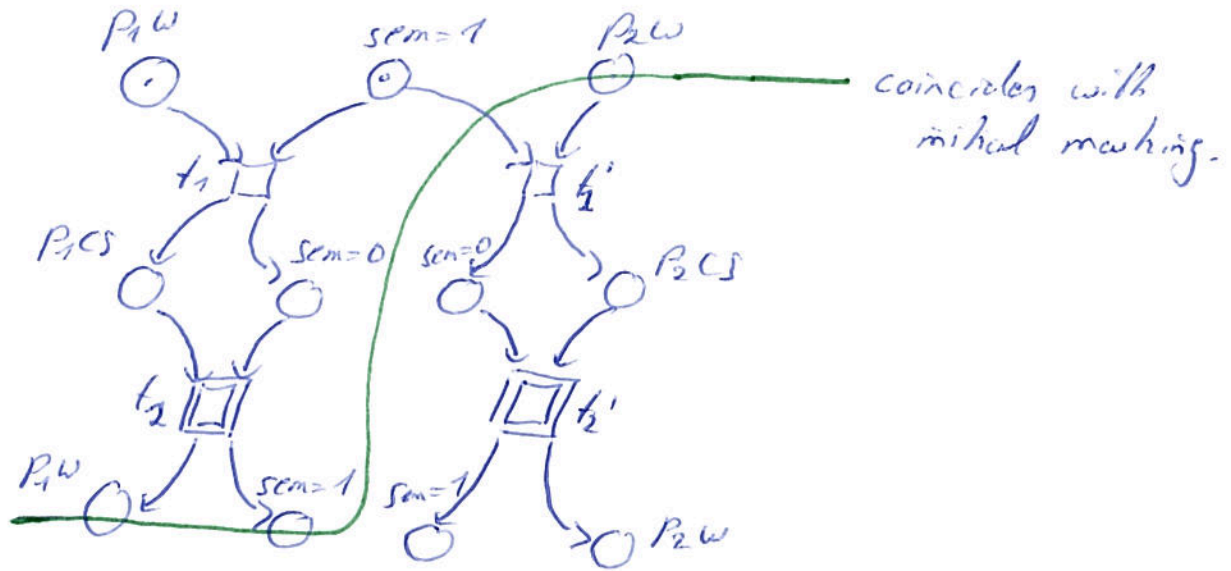
Idea: Perform changes locally.

Technically:

Compute an acyclic version of the net

- ↳ Every token yields a place
- ↳ Insert fresh instances of transitions.

In the example:



from here, the unfolding starts repeating and can be truncated.

Encode unfolding into SAT:

$$U = \underbrace{(t_2 \Rightarrow t_1) \wedge (t_2' \Rightarrow t_1')}_{\text{causally closed}} \wedge \underbrace{(t_1 \Rightarrow \neg t_1') \wedge (t_1' \Rightarrow \neg t_1)}_{\text{conflict free}}$$

Is $M = \begin{pmatrix} ? \\ 1 \\ ? \\ 1 \\ 2 \\ ? \end{pmatrix}$ reachable?

\Leftrightarrow t_1 and t_1' can be fired without t_2 or t_2' in between in some sequence.

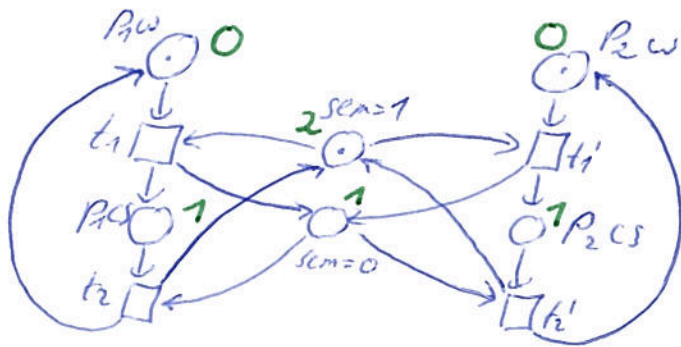
But $U \wedge t_1 \wedge t_1' = \text{false}$

Return "unreachable".

□

Invariants:

Weight tokens on places



Weighted sum of tokens stays constant in every reachable marking M :

$$2M(sem=1) + M(p_{1cs}) + M(p_{2cs}) + M(sem=0) = 2$$

init: ✓

17/10 t_1 : $2 \cdot 0 + 1 + 0 + 1 = 2$

17/10 t_1' : $2 \cdot 0 + 0 + 1 + 1 = 2$

Proving mutual exclusion (with invariants)

↳ M reachable with $M(p_{1cs}) = 1 = M(p_{2cs}) = M(sem=0)$?

Equation has to be satisfied:

$$2M(sem=1) + M(p_{1cs}) + M(p_{2cs}) + M(sem=0) = 2M(sem=1) + 1 + 1 + 1$$

$$\Rightarrow 3$$

$$\neq 2.$$

Return "marking is not reachable, mutual exclusion holds".

How to compute the weights?

Use linear algebra.

connectivity matrix

$$C = \begin{matrix} & t_1 & t_1' & t_2 & t_2' \\ \begin{matrix} P_{1w} \\ P_{1cs} \\ P_{2w} \\ P_{2cs} \\ sem=1 \\ sem=0 \end{matrix} & \begin{pmatrix} -1 & 0 & 1 & 0 \\ 1 & 0 & -1 & 0 \\ 0 & -1 & 0 & 1 \\ 0 & 1 & 0 & -1 \\ -1 & -1 & 1 & 1 \\ 1 & 1 & -1 & -1 \end{pmatrix} \end{matrix}$$

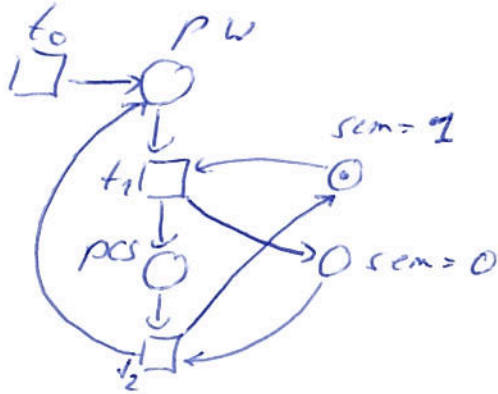
Invariants are solutions to $C^T x = 0$.

In the example:

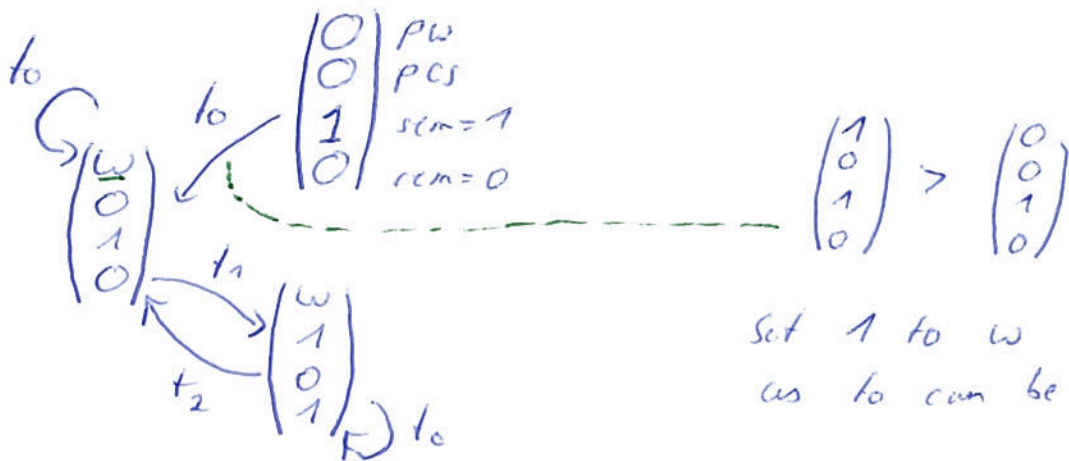
$$\begin{pmatrix} -1 & 1 & 0 & 0 & -1 & 1 \\ 0 & 0 & -1 & 1 & -1 & 1 \\ 1 & -1 & 0 & 0 & 1 & -1 \\ 0 & 0 & 1 & -1 & 1 & -1 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \\ 0 \\ 1 \\ 2 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} \quad \checkmark$$

Coverability graphs:

Consider an infinite state version of the example:



Coverability graph is an abstract version of the transition system



Set 1 to w
as t_0 can be repeated.

Mutual exclusion still holds. \checkmark

□