

## 11.3 Multi-headed Automata

Goal: Develop an automaton model

↳ suitable for normal-form computations

↳ closed under regular intersection

(to check for happens-before cycles)

↳ for which emptiness is easy to check

Idea: • Generate a computation  $\sigma_1 \dots \sigma_n$

by simultaneously generating the parts  $\sigma_i$ .

• Automaton has a head for each part.

Transition relation defines the head

that produces a letter.

Definition: • An  $n$ -headed automaton over the (finite) alphabet  $\Sigma$

is a tuple  $\mathcal{A} = (S, [1, n] \times \Sigma, \rightarrow, s_0, S_f)$

with

• finite set of states  $S$ , initial state  $s_0 \in S$ , final states  $S_f \subseteq S$ ,

• transition relation  $\rightarrow \subseteq S \times ([1, n] \times \Sigma) \times S$ .

• The language of  $\mathcal{A}$  is

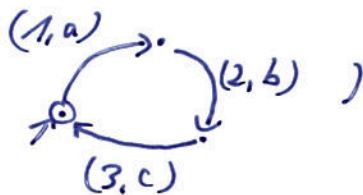
$$\mathcal{L}(\mathcal{A}) := \{ \pi_2(\sigma \downarrow (\{1\} \times \Sigma) \dots \sigma \downarrow (\{n\} \times \Sigma)) \mid s_0 \xrightarrow{\sigma} s \in S_f \}$$

Here,  $\pi_2((a_1, b_1) \dots (a_k, b_k)) := b_1 \dots b_k$

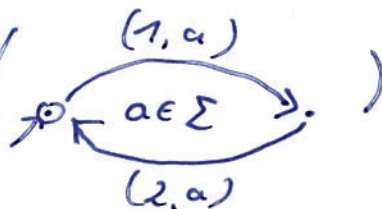
is the projection to the second component.

Example:

•  $\{ a^n b^n c^n \mid n \in \mathbb{N} \} = \mathcal{L} \left( \begin{array}{c} \text{Diagram 1} \end{array} \right)$



•  $\{ w.w \mid w \in \Sigma^* \} = \mathcal{L} \left( \begin{array}{c} \text{Diagram 2} \end{array} \right)$



Both languages are known to be not context-free.

•  $\{w, w^{\text{reverse}} \mid w \in \Sigma^*\}$

The language is context-free but cannot be accepted by a multi-headed automaton.

Together, we note that context-free languages and the languages of multi-headed automata are incompatible.

Lemma (Closure under Regular Intersection):

Consider an  $n$ -headed automaton  $A$  and a finite automaton  $B$  over a common alphabet  $\Sigma$ . There is an  $n$ -headed automaton  $A \parallel B$  with

$$L(A \parallel B) = L(A) \cap L(B).$$

Proof:

Idea:

- Guess the states of  $B$  that we reached, when the  $v_i$  have been processed.
- Check the guess in the end.

Construction:

Let  $A = (S, [1, n], \Sigma, \rightarrow_A, s_0, S_F)$

$B = (Q, \Sigma, \rightarrow_B, q_0, Q_F)$ .

Define  $A \parallel B := (\{s_{new}\} \cup S \times Q^n \times Q^n, \rightarrow, s_{new}, F)$

with

$F := \{ (s, \overline{q_{\text{init}}}, \overline{q_{\text{current}}}) \mid \overline{q_{\text{current}}}(i) = \overline{q_{\text{init}}}(i+1) \text{ for all } 1 \leq i < n$

and  $\overline{q_{\text{current}}}(n) \in Q_F \text{ and } s \in S_F \}$

$S_{new} \xrightarrow{\epsilon} (s_0, \overline{q}, \overline{q})$  for all  $\overline{q} \in Q^n$  where  $\overline{q}(1) = q_0$   
and

$$(s, \overline{q_{init}}, \overline{q_{current}} [c_i := q]) \xrightarrow{a} (s', \overline{q_{init}}, \overline{q_{current}} [c_i := q']),$$

$$\text{if } s \xrightarrow{(c_i, a)}_{\mathcal{A}} s' \text{ and } q \xrightarrow{a}_{\mathcal{B}} q'.$$

Remark:

Multi-headed automata are not effectively closed under intersection nor under shuffle.

Proof:

Reduce Post's correspondence problem (PCP) to an intersection of multi-headed automata:

the PCP instance has a solution  
iff the intersection is not empty.

Since emptiness for MHTA is decidable,  
the intersection can at least not be computable. □

Lemma:

Emptiness for MHTA is NL-complete.

Proof:

Emptiness amounts to disproving  
the existence of a path from initial to final state.

This problem is known as  $\overline{PATH}$ .

It is in NL by the Immerman-Szelepcsényi theorem. □

## 11.4 From Normal-Form Computations to MHF

Goal: Encode the normal-form computations  $\tau \in \text{PSO}(P)$  as the language of a multi-headed automaton.

Construction:

Consider program  $P$ .

Define the 3-headed automaton

$$\overline{A}_P := (S, [1,3] \times \text{FACT}, \rightarrow, s_0, S)$$

where

$$S := \{ (pc, val, buf, pwt) \}$$

$$pc: \text{TID} \rightarrow \text{LOC}$$

$$val: \text{VAR} \rightarrow \text{DOM}$$

$$buf: \text{TID} \times \text{DOM} \rightarrow \underbrace{\text{DOM}}_{\text{fick}}$$

$$pwt: \text{TID} \times \text{DOM} \rightarrow \{1,2,3\}$$

Idea:

$pc$  = current control state (in  $\tau$ )

$val$  = current variable valuation (in  $\tau$ )

$buf$  = last buffered store per thread per address

$pwt$  = for each thread and each address

part of the computation

where to generate next store

$$s_0 := \{ (pc_0, val_0, buf_{\perp}, pwt_{\perp}) \}$$

$$pc_0(t) := l_0^t$$

$$val_0(a, t) := 0$$

$$buf_{\perp}(t, a) := \perp$$

$$pwt_{\perp}(t, a) := 1 \}$$

The transition relation is again defined by rules.

In the following, let  $pc(t) = l$  and set  $pc' := pc[t := l']$ .

$$\text{(ldnewly)} \quad \frac{l: r \leftarrow \text{mem}[r'] \text{ goto } l', \text{ val}(r') = a, \text{ buf}(t, a) = v}{(pc, \text{val}, \text{buf}, \text{pwt}) \xrightarrow{(1, (t, l, a))} (pc', \text{val}[r := v], \text{buf}, \text{pwt})}$$

$$\text{(ldmem)} \quad \frac{l: r \leftarrow \text{mem}[r'] \text{ goto } l', \text{ val}(r') = a, \text{ buf}(t, a) = \perp, \text{ val}(a) = v}{(pc, \text{val}, \text{buf}, \text{pwt}) \xrightarrow{(1, (t, l, a))} (pc', \text{val}[r := v], \text{buf}, \text{pwt})}$$

$$\text{(stmem)} \quad \frac{l: \text{mem}[r] \leftarrow r' \text{ goto } l', \text{ val}(r) = a, \text{ val}(r') = v, \text{ pwt}(t, a) = 1}{(pc, \text{val}, \text{buf}, \text{pwt}) \xrightarrow{(1, (t, \text{isu}, a)). (1, (t, st, a))} (pc', \text{val}[a := v], \text{buf}, \text{pwt})}$$

$$\text{(stdelay)} \quad \frac{l: \text{mem}[r] \leftarrow r' \text{ goto } l', \text{ val}(r) = a, \text{ val}(r') = v, \text{ pwt}(t, a) = i > 1}{(pc, \text{val}, \text{buf}, \text{pwt}) \xrightarrow{(1, (t, \text{isu}, a)). (i, (t, st, a))} (pc', \text{val}, \text{buf}[(t, a) := v], \text{pwt})}$$

(local) is easy

$$\text{(mfence)} \quad \frac{l: \text{mfence goto } l', \text{ buf}(t, a) = \perp \text{ for all } a \in \text{DOM}}{(pc, \text{val}, \text{buf}, \text{pwt}) \xrightarrow{(1, (t, \text{mfence}))} (pc', \text{val}, \text{buf}, \text{pwt})}$$

$$\text{(pwt)} \quad \frac{\text{pwt}(t, a) = i, j > i}{(pc, \text{val}, \text{buf}, \text{pwt}) \xrightarrow{\epsilon} (pc, \text{val}, \text{buf}, \text{pwt}[(t, a) := j])}$$

Claim:  
 $L(\text{FP}) = \{ \tau \in \text{CPSO}(P) \mid \tau \text{ is in normal form} \}$ .

### 16.5 Finding Cycles

Goal: Check if a normal-form computation in  $L(\text{FP})$  has cyclic happens-before.

Problem: Cycles in normal-form computations can be complicated.

Idea: Whenever a computation has a cycle, it has one where each thread that is involved is entered and left precisely once.

Lemma:

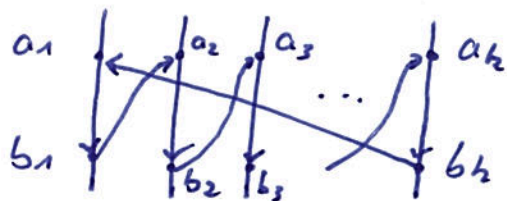
• Computation  $\tau \in \text{CPSO}(P)$  is violating iff there is a cycle

$$a_1 \xrightarrow{p_0} b_1 \xrightarrow[\text{src, st, cf}]{\text{src}} a_2 \xrightarrow{p_0} b_2 \xrightarrow[\text{src, st, cf}]{\text{src}} a_3 \dots b_k \xrightarrow[\text{src, st, cf}]{\text{src}} a_1,$$

with  $\text{thread}(a_i) = \text{thread}(b_i) = t_i \neq t_j = \text{thread}(a_j) = \text{thread}(b_j)$  for all  $i \neq j$

• We call the sequence  $t_1 \dots t_k$  the type of the cycle.

Illustration:

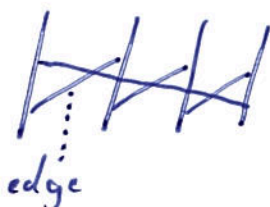


Problem: Even such simpler cycles are hard to detect: the actions constituting the cycle may not occur in this order in the computation.

Idea: (1) Guess  $b_i$  and  $a_{i+1}$  in the computation  
(2) Check that  $b_i \xrightarrow[\text{src, st, cf}]{\text{src}} a_{i+1}$  holds.

For (1): Extend  $\mathbb{R}_P$  to  $\mathbb{R}_P^*$  so as to make  $b_i$  and  $a_{i+1}$  by  $m \in \mathbb{P}(\{\text{enter}, \text{leave}\})$ .

For (2): Use a regular intersection, i.e., one finite automaton for each edge in



Let  $A^{cyc}$  be the product of the finite automata  $A^{edge}$  for all edges in cycle type  $cyc$ .

Theorem:

$P$  is robust iff  $L(A_P^*) \cap L(A^{cyc}) = \emptyset$   
for all cycle types  $cyc$ .